

MAT3012-MIDTERM 2.DERS

VECTOR and MATRICES

• Row vector = $\begin{bmatrix} 2 & 4 & 5 \end{bmatrix}$

• Column vector = $\begin{bmatrix} 2 \\ 4 \\ 5 \end{bmatrix}$

• $A = a_{ij}$ $\underset{\text{column}}{\overset{m \times n}{\text{row}}} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}_{m \times n}$

• Transpose of Matrix

A of size $m \times n$ is the matrix of A^T of size $n \times m$

• $(A^T)^T = A$

• $(A \cdot B)^T = A^T \cdot B^T$

• The addition matrix

$$A = \begin{bmatrix} 1 & 2 \\ -2 & 5 \end{bmatrix}, B = \begin{bmatrix} 3 & 0 \\ 1 & 2 \end{bmatrix} \Rightarrow A + B = \begin{bmatrix} 4 & 2 \\ -1 & 7 \end{bmatrix}$$

• The product of matrices $A(m \times n)$ by $B(n \times p) = C(m \times p)$

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}, B = \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \end{bmatrix} \rightarrow C = \begin{bmatrix} a & c & e \\ b & d & f \end{bmatrix}$$

$$\begin{aligned} a &= 1 \times 1 + 2 \times -1 = -1 \\ b &= 3 \times 1 + 4 \times -1 = -1 \end{aligned}$$

$$c = 1 \times 0 + 2 \times 1 = 2$$

$$d = 3 \times 0 + 4 \times 1 = 4$$

$$\begin{aligned} e &= 1 \times 1 + 2 \times 0 = 1 \\ f &= 3 \times 1 + 4 \times 0 = 3 \end{aligned} \quad \left. \begin{array}{l} \{ \\ \} \end{array} \right\} C = \begin{bmatrix} -1 & 2 & 1 \\ -1 & 4 & 3 \end{bmatrix}$$

• Determinant

$$\begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} = a_{11} \times a_{22} - a_{12} \times a_{21}$$

$$\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{11} \cdot \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \cdot \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \cdot \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$$

3) Gauss Elimination Method

- First suppose we have a system of equation which is on upper triangular form

- And backward substitution

Example: $\begin{cases} x_1 + x_2 - 2x_3 = -3 & x_3 = 2 \\ 3x_2 + 6x_3 = -1 & x_2 = -3 \\ 5x_3 = 10 & x_1 = 4 \end{cases}$

Important!!!

The order of two rows can be changed

Multiplying a row by nonzero constant

Multiplying a row by nonzero constant

The row can be replaced by the sum of that row and nonzero multiple of any other row

Example

$$\begin{cases} 4x_1 - 2x_2 + x_3 = 15 \\ -3x_1 - x_2 + 4x_3 = 8 \\ x_1 - x_2 + 3x_3 = 13 \end{cases}$$

$$\left[\begin{array}{ccc|c} 4 & -2 & 1 & 15 \\ -3 & -1 & 4 & 8 \\ 1 & -1 & 3 & 13 \end{array} \right]$$

$$\Rightarrow \left[\begin{array}{ccc|c} 4 & -2 & 1 & 15 \\ 0 & -10 & 19 & 77 \\ 0 & 2 & -11 & -37 \end{array} \right] \begin{matrix} R_2 = 3R_1 + 4R_2 \\ R_3 = R_1 - 4R_3 \end{matrix} \Rightarrow \left[\begin{array}{ccc|c} 4 & -2 & 1 & 15 \\ 0 & -10 & 19 & 77 \\ 0 & 2 & -11 & -37 \end{array} \right] R_3 = R_2 + 5R_3$$

$$x_3 = \frac{108}{36} = 3 \quad \begin{matrix} -10x_2 + 19x_3 = 77 \\ -10x_2 + 57 = 77 \\ -20 = 10x_2 \\ x_2 = 2 \end{matrix}$$

$$\begin{matrix} 4x_1 - 2x_2 + x_3 = 15 \\ 4x_1 + 4 + 3 = 15 \\ 4x_1 = 8 \\ x_1 = 2 \end{matrix}$$

Gauss Elimination with Partial Pivoting

Example

$$\begin{cases} x_1 + 5x_2 + 3x_3 = 10 \\ x_2 + 3x_2 + 2x_3 = 5 \\ 2x_1 + 4x_2 - 6x_3 = -4 \end{cases}$$

$$\left[\begin{array}{ccc|c} 1 & 5 & 3 & 10 \\ 0 & 1 & 2 & 5 \\ 2 & 4 & -6 & -4 \end{array} \right] = \left[\begin{array}{ccc|c} 2 & 4 & -6 & -4 \\ 0 & 1 & 2 & 5 \\ 1 & 5 & 3 & 10 \end{array} \right] \begin{matrix} R_2 = R_2 - \frac{1}{2}R_1 \\ R_3 = R_3 - \frac{1}{2}R_1 \end{matrix}$$

$$\left[\begin{array}{ccc|c} 2 & 4 & -6 & -4 \\ 0 & 1 & 2 & 5 \\ 0 & 1 & 5 & 3 \end{array} \right] \begin{matrix} R_3 = R_3 - \frac{1}{3}R_2 \\ 3x_2 = 3 \\ x_2 = 1 \end{matrix}$$

$$\begin{matrix} 3x_2 + 6x_3 = 12 & 2x_1 + 4x_2 + 6x_3 = -4 \\ 3x_2 + 6 = 12 & 2x_1 + 8 - 6 = -4 \\ 3x_2 = 6 & 2x_1 + 2 = -4 \\ x_2 = 2 & 2x_1 = -6 \\ & x_1 = -3 \end{matrix}$$

- Pivoting Method is better.

②

Use the Gaussian elimination method with backward substitution and two-digit rounding arithmetic to solve the following linear systems. Do not reorder the equations (The exact solution is $x_1 = 1, x_2 = -1, x_3 = 3$).

$$\begin{cases} 4x_1 - x_2 + x_3 = 8, \\ 2x_1 + 5x_2 + 2x_3 = 3 \\ x_1 + 2x_2 + 4x_3 = 11 \end{cases}$$

$$\left[\begin{array}{ccc|c} 4 & -1 & 1 & 8 \\ 2 & 5 & 2 & 3 \\ 1 & 2 & 4 & 11 \end{array} \right] \begin{array}{l} R_2 = R_2 - \frac{1}{2}R_1 \\ R_3 = R_3 - \frac{1}{4}R_1 \end{array} = \left[\begin{array}{ccc|c} 4 & -1 & 1 & 8 \\ 0 & 5.5 & 1.5 & -1 \\ 0 & 2.25 & 3.75 & 9 \end{array} \right] \begin{array}{l} R_3 = 5.5R_3 - 2.25R_2 \\ 5.5x_2 + 1.5x_3 = -1 \\ 5.5x_2 + 4.5 = -1 \\ 5.5x_2 = -5.5 \\ x_2 = -1 \end{array}$$

$$\left[\begin{array}{ccc|c} 4 & -1 & 2 & 8 \\ 0 & 5.5 & 1.5 & -1 \\ 0 & 0 & 17.25 & 51.75 \end{array} \right] \begin{array}{l} 17.25x_3 = 51.75 \\ x_3 = 3 \end{array}$$

$$\begin{array}{l} 4x_1 - x_2 + x_3 = 8 \\ 4x_1 + 1 + 3 = 8 \\ 4x_1 = 4 \\ x_1 = 1 \end{array}$$

Use the Gaussian Elimination method to solve the following linear systems. Determine whether trivial pivoting is needed.

a) $\begin{cases} 2x_1 - 1.5x_2 + 3x_3 = 1, \\ -x_1 + 2x_3 = 3 \\ 4x_1 - 4.5x_2 + 5x_3 = 1 \end{cases}$

b) $\begin{cases} x_1 - x_2 + 3x_3 = 2, \\ 3x_1 - 3x_2 + x_3 = -1 \\ x_1 + x_2 = 3 \end{cases}$

a) $\left[\begin{array}{ccc|c} 2 & -1.5 & 3 & 1 \\ -1 & 0 & 2 & 3 \\ 4 & -4.5 & 5 & 1 \end{array} \right]$ pivoting is needed $\Rightarrow \left[\begin{array}{ccc|c} 4 & -4.5 & 5 & 1 \\ 2 & -1.5 & 3 & 1 \\ -1 & 0 & 2 & 3 \end{array} \right] R_2 = R_2 - \frac{1}{2}R_1$

$$\left[\begin{array}{ccc|c} 4 & -4.5 & 5 & 1 \\ 0 & 0.75 & 0.5 & 0.5 \\ 0 & -4.5 & 13 & 13 \end{array} \right] = \left[\begin{array}{ccc|c} 4 & -4.5 & 5 & 1 \\ 0 & -4.5 & 13 & 13 \\ 0 & 0.75 & 0.5 & 0.5 \end{array} \right] R_3 = 6R_3 + R_2 \Rightarrow \left[\begin{array}{ccc|c} 4 & -4.5 & 5 & 1 \\ 0 & -4.5 & 13 & 13 \\ 0 & 0 & 16 & 16 \end{array} \right]$$

$$\begin{array}{l} 16x_3 = 16 \\ x_3 = 1 \end{array} \quad \begin{array}{l} -4.5x_2 + 13x_3 = 13 \\ -4.5x_2 + 13 = 13 \\ x_2 = 0 \end{array} \quad \begin{array}{l} 4x_1 - 4.5x_2 + 5x_3 = 1 \\ 4x_1 + 5 = 1 \\ 4x_1 = -4 \\ x_1 = -1 \end{array}$$

(3)

Error in Numerical Procedures

$$\text{Absolute error} = E_x = |x - \hat{x}|$$

$$\text{Relative error} = R_x = \frac{|x - \hat{x}|}{|x|}$$

- If the numbers are close to 1, $E_x \approx R_x$

- If the numbers are too high , we will use R_x

- If the numbers are too small , we will use E_x

Important Error Definition

- Round-off error: is the error due to storage of finite number of digit.

$$p = \frac{22}{7} = 3.1428571428 \dots$$

$$f_{\text{chip}} = 0.314285 \times 10^{-1}$$

$$f_{\text{round}} = 0.314286 \times 10^{-1}$$

- Input error = is the error in input data

- Propagation error = is the error in the output due to error in input data

- Computational error = is the error during arithmetic operations.

- Truncation error = is the error of approximately expression in place of exact expression

- Loss of Significance = caused by bad subtraction which means a subtraction of number from another one that is almost equal in value.

Taylor's Theorem

If $f(x)$ has continuous $(n+1)$ derivatives on (a,b) then for any point x and x_0 from (a,b)

$$f(x) = \sum_{k=0}^n \frac{f^{(k)}(x_0)}{k!} \cdot (x-x_0)^k + \underbrace{\frac{1}{(n+1)!} \cdot f^{(n+1)}(\xi) \cdot (x-x_0)^{n+1}}_{E_n(x)}$$

Theorem: If $|f^{(n+1)}(\xi)| \leq M$ for any ξ between x and x_0 then,

$$|E_n(x)| \leq M \cdot \frac{(x-x_0)^{n+1}}{(n+1)!}$$

Example

using Taylor approximation for the function of $f(x)=e^x$ about $x_0=0$ [C0,1]

$$f(x) = e^x = f(0) = 1$$

$$f'(x) = e^x = f'(0) = 1$$

$$f''(x) = e^x = f''(0) = 1$$

$$f'''(x) = e^x = f'''(0) = 1$$

$$f^{(4)}(x) = e^x = f^{(4)}(0) = 1$$

$$f(x) = 1 + x + \underbrace{\frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!}}_{P_3(x)} + E_4(x)$$

$$P_3(x) = 1 + 1 + \frac{1}{2} + \frac{1}{6} = \frac{8}{3} \approx 2.6667$$

$$E_4(x) = e - 2.6667 = 0.1132617$$

④

Let $f(x) = 2x \cos(2x) - (x-2)^2$ and $x_0 = 0$.

- Find the third Taylor polynomial $P_3(x)$, and use it to approximate $f(0.4)$.
- Use the error formula in Taylor's Theorem to find an upper bound for the error $|f(0.4) - P_3(0.4)|$. Compute the actual error.
- Find the third Taylor polynomial $P_4(x)$, and use it to approximate $f(0.4)$.
- Use the error formula in Taylor's Theorem to find an upper bound for the error $|f(0.4) - P_4(0.4)|$. Compute the actual error.

$$\begin{aligned} f(x) &= 2x \cos(2x) - (x-2)^2 \text{ and } x_0 = 0 \\ f'(x) &= -4x \sin(2x) + 2 \cos(2x) - 2(x-2) = -4x \sin(2x) + 2 \cos(2x) - 2x + 4 \\ f''(x) &= -8x \cos(2x) - 8 \sin(2x) - 2 \\ f'''(x) &= 16x \sin(2x) - 24 \cos(2x) \\ f^{(4)}(x) &= 32x \cos(2x) + 64 \sin(2x) \\ f^{(5)}(x) &= 160 \cos(2x) - 64 \sin(2x) \end{aligned}$$

$$1) P_3(x) = -4 + 6x - \frac{2x^2}{2} + \frac{24x^3}{6} = -4 + 6x - x^2 + 4x^3$$

$$f(0.4) \approx P_3(0.4) = -4(0.4)^3 - (0.4)^2 + 6(0.4) - 4 = -2.016$$

$$b) E_3 = |f(0.4) - P_3(0.4)|$$

$$E_3 \leq |f^{(4)}(\varepsilon) \cdot \frac{x^4}{4!}| \quad \varepsilon \in (0, 0.4)$$

$$f^{(4)}(\varepsilon) = 32 \cdot (0.4) \cos(0.8) + 64 \sin(0.8) = 55$$

$$E_3 = 55 \cdot \frac{(0.4)^4}{4!} = 0.058$$

$$\begin{aligned} \Rightarrow f(0) &= -4 & \Rightarrow f'(0) &= 6 \\ \Rightarrow f''(0) &= -2 & \Rightarrow f'''(0) &= -24 \\ \Rightarrow f^{(4)}(0) &= 0 & \Rightarrow f^{(5)}(0) &= 0 \end{aligned}$$

$$\text{Actual error} = |f(0.4) - P_3(0.4)|$$

$$f(0.4) = 2(0.4) \cdot \cos(0.8) - (0.4 - 2)^2 = 2.002635$$

$$|2.002635 - 2.016| = 0.013365$$